Robot V 1.23



SPECIFICATIONS:

* 6 Motor HS drive
* Two drive chains
* 4 wheels
* Aluminium structure
* 4 motor lift
* Three stage lift
* 2 motor claw

DIMENTIONS:

17.5” \* 15” \* 17.5 when not extended

**What needs to be changed:**

* Plug in shaft encoders
* Make it straight
* Mount claw

By Robbie Buxton

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**Overview:**

The parts we needed to make the third stage finally arrived (two 12 tooth sprockets) today so we could complete the lift. The linear action works very well however it a bit lopsided which is something we will need to fix. After we mount the claw the core robot will be basically finished and all that will be needed to done will be tweaking.

**WHAT HAS BEEN CHANGED:**

* Added third stage